

# OAK-D-IOT-75

## ⚠ Warning

OAK IoT series is now **community supported only**, and is **provided as-is**. This means we most likely **won't update it** and **we don't provide support** for it (Discord, forums, email...).

[Buy it on Luxonis shop](#)



## Overview

The **OAK-D-IoT-75** baseboard has three on-board cameras which implement stereo and RGB vision, piped directly into the [OAK-SoM-IoT](#) for depth and AI processing. The data can be then output to a host via USB 3.1 Gen1 (Type-C) or via ESP32 WiFi interface. If you are **new** to **OAK IOT devices**, you can check [Getting started with OAK IoT devices](#) tutorial.

This design is one of two baseboards for the [OAK-SoM-IoT](#), the other one being [OAK-D-IOT-40](#). The only difference is the the stereo baseline distance and the shape/size of the OAK camera.

## Hardware specifications

This OAK camera uses USB-C cable for communication and power. It supports both USB2 and USB3 (5Gbps / 10Gbps).

# Camera module specifications

You can select either Fixed Focus (FF) or Auto Focus (AF) color camera, more [information here](#).

Camera Specs	Color camera	Stereo pair
Sensor	IMX378 (PY004 AF, PY052 FF)	OV9282 (PY003)
DFOV / HFOV / VFOV	81° / 69° / 55°	89° / 80° / 55°
Resolution	12MP (4056x3040)	1MP (1280x800)
Focus	AF: 8cm - ∞ or FF: 50cm - ∞	FF: 19.6cm - ∞
Max Framerate	60 FPS	120 FPS
F-number	1.8 ±5%	2.0 ±5%
Lens size	1/2.3 inch	1/4 inch
Effective Focal Length	4.81mm	2.35mm
Pixel size	1.55µm x 1.55µm	3µm x 3µm

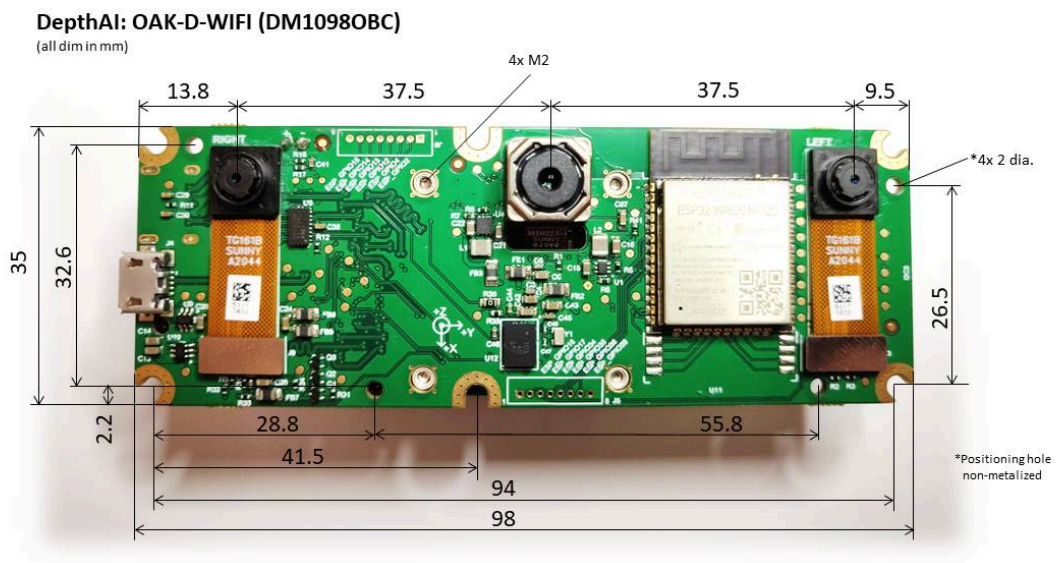
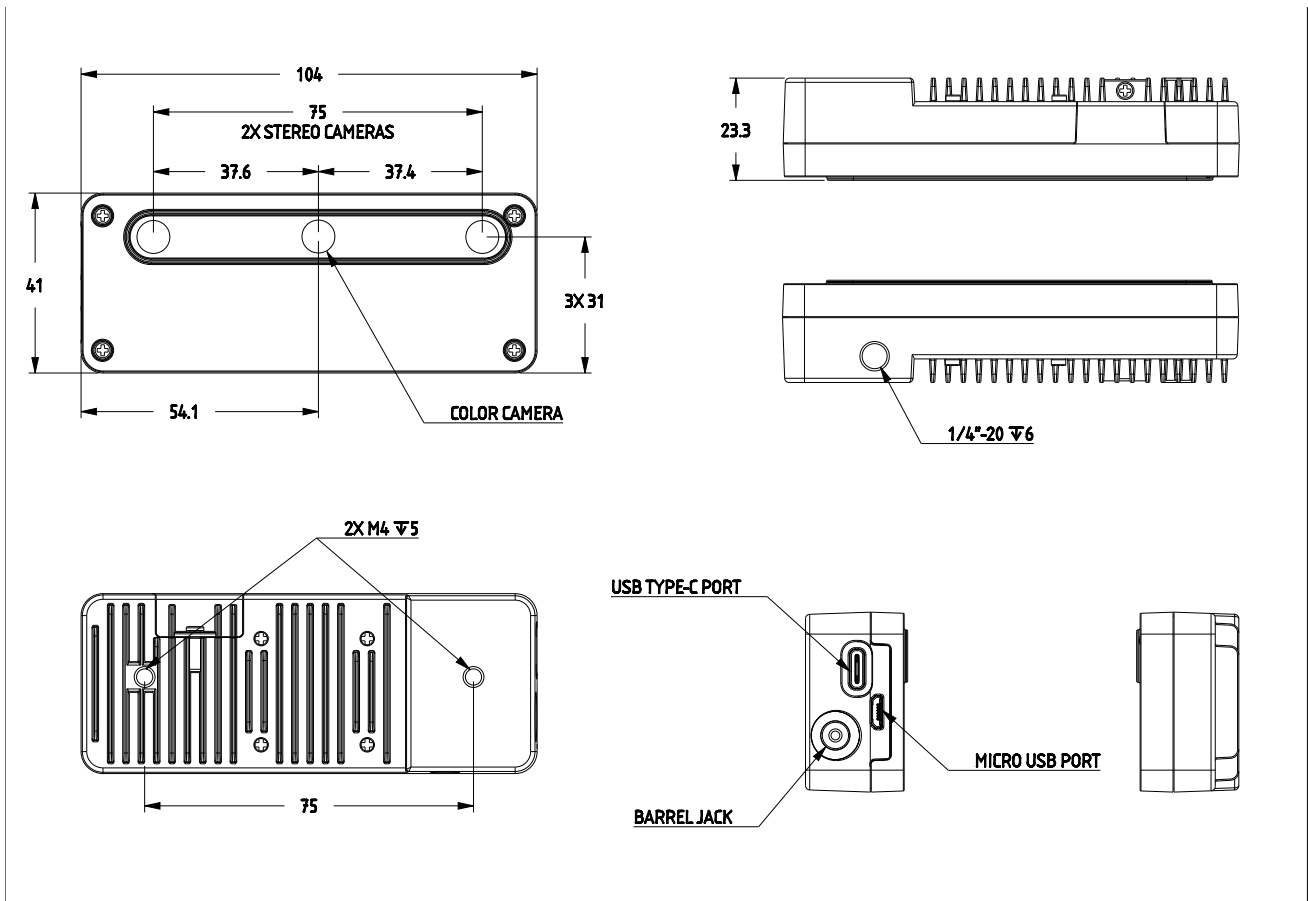
## RVC2 inside

This OAK device is built on top of the RVC2. Main features:

- **4 TOPS** of processing power (1.4 TOPS for AI - RVC2 NN Performance)
- **Run any AI model**, even custom-architected/built ones - models need to be converted.
- **Encoding:** H.264, H.265, MJPEG
- **Computer vision:** warp/dewarp, resize, crop via ImageManip node, edge detection, feature tracking. You can also run custom CV functions
- **Stereo depth** perception with filtering, post-processing, RGB-depth alignment, and high configurability
- **Object tracking:** 2D and 3D tracking with ObjectTracker node

## Dimensions and Weight

**Weight:** 89g total (with enclosure), 49g PCBA & SOM only



## Stereo depth perception

This OAK camera has a baseline of 7.5cm - the distance between the left and the right stereo camera. Minimal and maximal depth perception (MinZ and Max) depends on camera FOV, resolution, and baseline; more information here.

- Ideal depth range: 70cm - 12m
- MinZ: ~20cm (400P and extended), ~35cm (400P OR 800P, extended), ~70cm (800P)
- Median depth accuracy (See [800P, 75mm baseline distance OAKs](#) for details):

- below 4m: below 2% absolute depth error
- 4m - 7m: below 4% absolute depth error
- 7m - 10m: below 6% absolute depth error

## Getting started

OAK-D-IoT-75 Integrates ESP32-WROOM-32D (Wi-Fi 2.4 GHz to 2.5 GHz) and in terms of power consumption the device accepts 5V (+/-10%) from a 5.5mm x 2.5mm barrel jack or via USB 3.1 Gen1 Type-C

Interfacing with the [OAK-SoM-IoT](#) is also possible with DM1098OBC\_WiFi connector pads J5, and J6. These pads are designed for the Molex/53047-0810 or equivalent. Please refer to the schematics for pinout information.

The reset button resets the OAK-SoM-IoT only.

The 5V LED indicates 5V power is present on the DM1098OBC. The PG LED indicates “power good” from the OAK-SoM-IoT. The “RUN” LED indicates that the OAK-SoM-IoT is not in reset.

[Here is an example how to connect to the wifi and creates a basic http file server.](#)

## Power consumption

Most of the power is consumed by the [RVC2](#), so the power consumption mostly depends on the workload of the VPU:

- Base consumption + camera streaming: 2.5W - 3W
- AI subsystem consumption: Up to 1W
- Stereo depth pipeline subsystem: Up to 0.5W
- Video Encoder subsystem: Up to 0.5W

So the total power consumption can be up to ~5W if you are using all the features at 100% at the same time. To reduce the power consumption, you can reduce FPS of the whole pipeline - that way, subsystems won't be utilized at 100% and will consume less power.

## Operating temperature

The ambient operating temperature of [RVC2](#) based devices is between **-20°C and 50°C** when fully utilizing the VPU.

Similarly to the [Power consumption](#), max operating temperature depends on VPU utilization. The higher the VPU utilization, the more heat the VPU will generate. The RVC2 VPU can continuously operate at 105 °C, after which the depthai library will automatically shut down the device (to avoid chip damage).

To find out more, see our [Operative temperature range documentation](#).

## Datasheet

- [Datasheet](#)

## 3D Models

- Board STEP files [here](#)
- Enclosure STEP files [here](#)

## Files

- [Altium Design Files](#)
- [Assembly Drawing](#)
- [Assembly Outputs](#)
- [Fabrication Drawing](#)
- [Fabrication Outputs](#)
- [Schematic](#)

## Got questions?

Head over to [Discussion Forum](#) for technical support or any other questions you might have.